

# Vittorio Perera

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## WORK EXPERIENCES

### Lead Member of Technical Staff

*Salesforce, Inc.*

San Francisco, California, US

Enable voice interaction for Agentforce. Integrate the technology developed at Tenyx into Salesforce existing stack to deliver a fully configurable voice assistant to all the existing Salesforce customers.

Date: September 2024 - Present

### Founding Machine Learning Engineer

*Tenyx, Inc.*

Palo Alto, California, US

Realized the initial idea of a voice agent natively powered by LLMs into a product serving hundreds of calls every day. De-risked initial technology. Built first POC and developed it into a full-fledged product. Deployed and maintained Tenyx voice agents to serve live traffic.

Date: July 2022 - September 2024

### Applied Scientist

*Amazon - Lab 126*

Sunnyvale, California, US

Developed a deep learning-based approach to dialog management empowering developers to create natural, human-like voice experiences on Alexa. Trained and evaluated generative model enabling the automated generation of Alexa prompts, lifting the need for human authored inputs.

Date: November 2018 - June 2022

### Applied Scientist Intern

*Amazon - Lab 126*

Sunnyvale, California, US

Improved the ability for the Alexa voice assistant to understand and fulfill users' requests. Designed, trained and evaluated deep-learning models to parse users' utterances into a structured representation, the Alexa Meaning Representation Language (AMRL).

Date: May - August 2017

### Research Summer Intern

*IBM T.J. Watson Research Center*

Yorktown Heights, New York, US

Developed a multi-modal interface for a Pepper Robot to act as concierge for the Watson Research Center. Connected the robot with several IBM services (e.g., speech and face recognition), designed the robot dialog model, and developed a web interface to be displayed on the robot chest tablet.

Date: May - August 2016

## EDUCATION

### Carnegie Mellon University

Pittsburgh, Pennsylvania, US

Ph.D. in Computer Science (2018)

Thesis Title: *"Language-Based Bidirectional Human and Robot Interaction Learning for Mobile Service Robots"*

Advisor: Manuela Veloso

### Sapienza University

Rome, Italy

M.Sc. in Artificial Intelligence and Robotics (2013)

Thesis Title: *"Talking Robots: Voice User Interfaces For Human-Robot Interaction."*

Final Grade: 110/110 *cum laude*

**Sapienza University**

Rome, Italy

B.E. in Computer Engineering (2009)

Thesis Title: *"Parsing and Analysis of Medical Prescriptions"*

Final Grade: 101/110

**SELECTED  
PUBLICATIONS**

**Schema-Guided Natural Language Generation**

Authors: Yuheng Du, Shereen Oraby, Vittorio Perera, Minmin Shen, Anjali Narayan-Chen, Tagyoung Chung, Anu Venkatesh, Dilek Hakkani-Tur

*Proceedings of the 13th International Conference on Natural Language Generation (INLG), 2020*

**Multi-Task Learning For Parsing The Alexa Meaning Representation Language**

Authors: Vittorio Perera, Tagyoung Chung, Thomas Kollar, Emma Strubell.

*Proceedings of the AAAI Conference on Artificial Intelligence, 2018*

**Learning to Understand Questions on the Task History of a Service Robot**

Authors: Vittorio Perera, Manuela Veloso

*IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), 2017*

**Dynamic Generation and Refinement of Robot Verbalization**

Authors: Vittorio Perera, Sai Prabhakar Selveraj, Stephanie Rosenthal, Manuela Veloso

*IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), 2016*

**Learning Task-Relevant Environmental Knowledge from Human-Robot Dialog and the Web**

Authors: Thomas Kollar, Robin Soetens, Vittorio Perera, Mehdi Samadi, Yichao Sun, Daniele Nardi, René van de Molengraft, Manuela Veloso

*Robotics, 2015*

**Learning Environmental Knowledge from Task-Based Human-Robot Dialog**

Authors: Thomas Kollar, Vittorio Perera, Daniele Nardi, Manuela Veloso

*International Conference on Robotics and Automation, 2013*

**OTHER  
RESEARCH  
EXPERIENCES**

**Speaky For Robots**

Speaky for Robot was a project funded by the European Community, led by professor Daniele Nardi. The goal was to foster the definition and deployment of voice user interfaces in robotic applications where human-robot interaction is required.

<http://www.echord.info/wikis/website/speaky>

**LANGUAGES**

*Italian* - Native

*English* - Fluent

*French* - Intermediate